

CISC 7310X
C04d: Thread Issues

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Acknowledgement

- This slides are a revision of the slides by the authors of the textbook

Outline

- Threading Issues
 - Semantics of `fork()` and `exec()`
 - Signal handling
 - Thread cancellation
 - Thread-local storage
 - Scheduler Activations
- Operating System Examples

Thread Issues

- Semantics of `fork()` and `exec()` system calls
- Signal handling
 - Synchronous and asynchronous
- Thread cancellation of target thread
 - Asynchronous or deferred
- Thread-local storage
- Scheduler Activations

Semantics of `fork()` and `exec()`

- Does `fork()` duplicate only the calling thread or all threads?
 - Some UNIXes have two versions of `fork`
- `exec()` usually works as normal - replace the running process including all threads

Signal Handling

- Signals are used in UNIX systems to notify a process that a particular event has occurred.
- A signal handler is used to process signals
 - Signal is generated by particular event
 - Signal is delivered to a process
 - Signal is handled by one of two signal handlers:
 - default
 - user-defined
- Every signal has default handler that kernel runs when handling signal
 - User-defined signal handler can override default
 - For single-threaded, signal delivered to process

Signal Handling

- Where should a signal be delivered for multi-threaded?
 - Deliver the signal to the thread to which the signal applies
 - Deliver the signal to every thread in the process
 - Deliver the signal to certain threads in the process
 - Assign a specific thread to receive all signals for the process

Thread Cancellation

- Terminating a thread before it has finished
- Thread to be canceled is **target thread**
- Two general approaches:
 - **Asynchronous cancellation** terminates the target thread immediately
 - **Deferred cancellation** allows the target thread to periodically check if it should be cancelled

Thread Cancellation: Pthreads

- Pthread code to create and cancel a thread:

```
pthread_t tid;

/* create the thread */
pthread_create(&tid, 0, worker, NULL);

. . .

/* cancel the thread */
pthread_cancel(tid);

/* wait for the thread to terminate */
pthread_join(tid, NULL);
```

Thread Cancellation: Pthreads

- Invoking thread cancellation requests cancellation, but actual cancellation depends on thread state

Mode	State	Type
Off	Disabled	–
Deferred	Enabled	Deferred
Asynchronous	Enabled	Asynchronous

- If thread has cancellation disabled, cancellation remains pending until thread enables it
- Default type is deferred
 - Cancellation only occurs when thread reaches **cancellation point**
 - i.e. `pthread_testcancel()`
 - Then **cleanup handler** is invoked
- On Linux systems, thread cancellation is handled through signals

Thread Cancellation: Java

- Deferred cancellation uses the `interrupt()` method, which sets the interrupted status of a thread.

```
Thread worker;  
  
. . .  
  
/* set the interruption status of the thread */  
worker.interrupt()
```

A thread can then check to see if it has been interrupted:

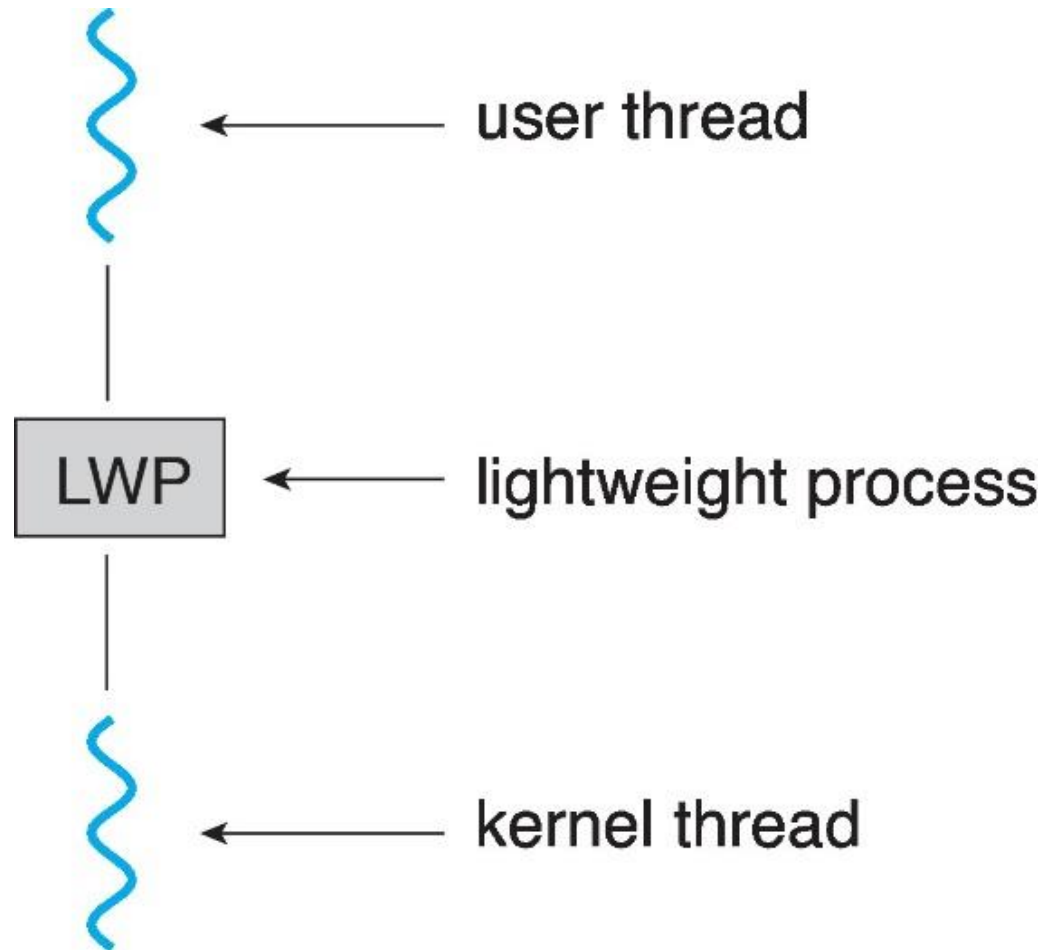
```
while (!Thread.currentThread().isInterrupted()) {  
    . . .  
}
```

Thread-local Storage

- **Thread-local storage (TLS)** allows each thread to have its own copy of data
- Useful when you do not have control over the thread creation process (i.e., when using a thread pool)
- Different from local variables
 - Local variables visible only during single function invocation
 - TLS visible across function invocations
- Similar to `static` data
 - TLS is unique to each thread

Scheduler Activations

- Both M:M and Two-level models require communication to maintain the appropriate number of kernel threads allocated to the application
- Typically use an intermediate data structure between user and kernel threads - **lightweight process (LWP)**
 - Appears to be a virtual processor on which process can schedule user thread to run
 - Each LWP attached to kernel thread
 - How many LWPs to create?
- Scheduler activations provide **upcalls** - a communication mechanism from the kernel to the **upcall handler** in the thread library
- This communication allows an application to maintain the correct number kernel threads



Questions?

- Threading Issues
 - Semantics of `fork()` and `exec()`
 - Signal handling
 - Thread cancellation
 - Thread-local storage
 - Scheduler Activations